



Universidad
de Alcalá



Safety through quality

CASE STUDY



Automating schedulability analysis of onboard software
on the Solar Orbiter

Case study: RVS

The Solar Orbiter is a joint project by the European Space Agency® (ESA) and the National Aeronautics and Space Administration® (NASA) to study the behaviour of the Sun. Due to be launched in 2017, the Solar Orbiter's payload of telemetry equipment includes the Energetic Particle Detector (EPD) suite of five telescopes, designed to measure the energy created by solar particles.



The University of Alcalá, the developers of the onboard software for the Instrument Control Unit (ICU) of the EPD, selected Rapita **Verification Suite (RVS)** to support schedulability analysis for the ICU software.

Automating schedulability timing analysis

Schedulability analysis aims to provide guarantees of deadline satisfaction. To automate the schedulability analysis of the on-board software, the project required an integration between **RVS** and the MAST (Modeling and Analysis Suite for real Time applications) analysis tool.

The University of Alcalá's integration was based on a new framework (MICOBS) for developing modeldriven component-based embedded software systems under a multi-platform approach and integrating different development and analysis technologies.

The project chose **RVS** to perform the on-target worst-case execution analysis. Apart from analysing the worst-case execution time (WCET), **RVS** could also measure code coverage in compliance with ESA's ECSS-E-40C standard, in addition to ISO 26262 and DO-178B guidelines.



Figure 1 – The Solar Orbiter

Summary

The challenge

- To create a measurement-based analysis of Solar Orbiter on-board software for schedulability.

The solution

- To collect worst-case execution time data for individual tasks using **RVS** integrated with other tools.

The benefits

- Developers were able to analyze different design alternatives with different elements with worst-case execution time (WCET) data.
- The effectiveness of the test suites were improved by measuring code coverage at the same time.

Challenge

To support automated schedulability analysis with measurement-based determination of WCET.

Solution

The preferred solution was to carry out tests of each of the components and service libraries that are part of the system using **RVS**. This means that schedulability analysis could be performed without the need to take timing measures on the complete system.

The overall schedulability analysis solution is based on the execution time measurements of:

- The component reactions to the reception of a message or the notification of an event
- The code of the service libraries

The WCET measurements are obtained by analysing each component and service library separately, using on-target measurement and subsequent WCET analysis based on the measurements. In order to perform the final system-level schedulability analysis, a transformation has to be used to obtain, from the MICOBS models, the appropriate MAST model.

The **RVS** toolset is used to perform the WCET analysis. Apart from analysing the WCET, the Rapi**Cover** component of the toolset is also capable of measuring code coverage in a variety of levels up to and including MC/DC.

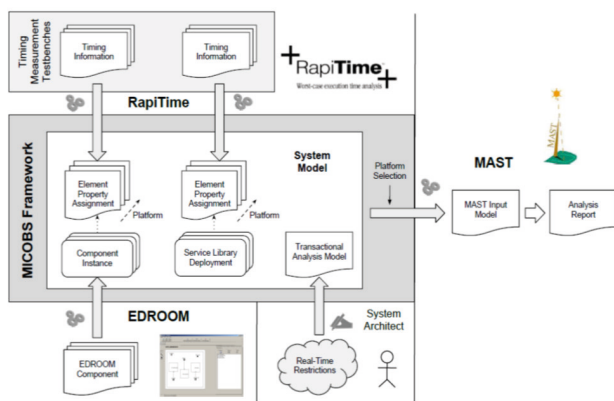


Figure 2 – Toolchain integration

In order to analyse the WCET using **RVS**, an appropriate set of test benches has to be defined. These test benches could comprise the unit tests used for software validation and code coverage analysis or they could be developed ad-hoc, a solution that, in principle, might provide a less pessimistic measurement of the WCET.

MICOBS allows the integration of the data obtained from **RVS** together with the specification of the configuration parameters that were used for each component or service library, as well as the platform on which they were run.

This information is used by MICOBS to create an instance of a particular analysis-oriented model (AOM) instance that will be later used during the transformation that will produce the MAST model of the complete system.

In this final stage, MICOBS forces the definition of the vector of parameter values used to configure each element and the platform on which the system is to be deployed.

Benefits

Using this integration, the developers could rapidly analyze different design alternatives with different elements once they had worst-case execution time (WCET) data.

Next steps

To learn how **RVS** can help reduce the cost and effort of software verification, see our product page at rapitasystems.com/products/rvs.

To enquire about what Rapita can do for you, contact us at info@rapitasystems.com.



About Rapita

Rapita Systems provides on-target software verification tools and services globally to the embedded aerospace and automotive electronics industries.

Our solutions help to increase software quality, deliver evidence to meet safety and certification objectives and reduce costs.

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